

TMR4M02BG/3BG/4BG/5BG/8BG

TMR Geartooth Sensor

Description

The TMR4M02BG/3BG/4BG/5BG/8BG geartooth sensors are composed of a dual-channel push-pull Wheatstone full bridge including eight high-sensitivity tunneling magnetoresistance (TMR) sensing elements. The placement of TMR sensing elements is designed for specific gear pitches in different gear modules. The dual-channel Wheatstone full bridge outputs two orthogonal sine and cosine signals with the rotation of the gears. The period of this signal equals to the gear pitch to measure the rotation position and direction of the gear.

The TMR4M02BG/3BG/4BG/5BG/8BG series are available in the compact LGA6L(3 mm × 6 mm × 0.9 mm) packages, with different configurations of gear pitches in following gear modules:

- TMR4M02BG: module 0.2
- TMR4M03BG: module 0.3
- TMR4M04BG: module 0.4
- TMR4M05BG: module 0.5
- TMR4M08BG: module 0.8

Features and benefits

- Tunneling magnetoresistance (TMR) technology
- · Adapt to gears of different modules
- High saturation field
- DC (zero speed) operation
- Sine/cosine signal output with accurate phase difference
- · Excellent thermal stability
- Excellent resistance to external magnetic field interference
- RoHS and REACH Compliant

Applications

- · Gear speed and direction measurement
- · Linear and angular speed sensing
- Linear and angular displacement sensing



LGA6L









Selection Guide

Part Number	Gear Module	Operating Ambient Temperature	Package	Packing Form
TMR4M02BG	0.2	-40 to 125°C	LGA6L	Tape & Reel
TMR4M03BG	0.3	-40 to 125°C	LGA6L	Tape & Reel
TMR4M04BG	0.4	-40 to 125°C	LGA6L	Tape & Reel
TMR4M05BG	0.5	-40 to 125°C	LGA6L	Tape & Reel
TMR4M08BG	0.8	-40 to 125°C	LGA6L	Tape & Reel

Catalogue

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1. Functional Block Diagram

The TMR4M02BG/3BG/4BG/5BG/8BG geartooth sensors use dual Wheatstone bridges of high sensitivity TMR sensing elements to increase the sensors' output signal amplitude with enhanced temperature characteristic and anti-interference performance as shown in Figure 1.



Figure 1. Block diagram

2. Operating Principle

The resistance value of the sensing elements changes with the target magnetic field, and the sensing direction is parallel to the chip surface as shown in Figure 2.



Figure 2. Sensing direction

The two bridges each output a sine wave signal with a phase difference of 90 degrees. The rotary position and direction of the gear can be calculated from the two output waveforms as shown in Figure 3.



Figure 3. Gear tooth rotational displacement

3. Pin Configuration



Figure 4. Pin configuration (LGA6L)

Number	Name	Function	
1	V1-	Phase A negative output	
2	V1+	Phase A positive output	
3	V _{cc}	Power supply	
4	V2+	Phase B positive output	
5	V2-	Phase B negative output	
6	GND	Ground	





4. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit	
Supply voltage	V _{cc}	-7	7	V	
Magnetic flux density	В	-	1500	Gs ¹⁾	
ESD performance (HBM)	V _{ESD}	-	4000	V	
Operating ambient temperature	T _A	-40	125	°C	
Storage ambient temperature	T _{stg}	-50	150	°C	

5. Electrical Specifications

 V_{CC} = 5 V, T_{A} = 25 °C, a 0.1 μF capacitor is connected between V_{CC} and GND

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply voltage	V _{cc}	operating	-	3	7	V
Bridge resistance	R _B	-	-	2 ²⁾	-	kΩ
Resistance temperature coefficient	TCR _B	B = 0 Gs	-	-0.10	-	%/°C
Offset	V _{OFFSET}	-	-20	-	20	mV/V

Notes:

1) 1 Oe (Oersted) = 1 Gauss in air = 0.1 millitesla = 79.8 A/m.

2) Bridge resistance (resistance between V_{cc} and GND at zero field) can be custom designed. Please contact MultiDimension Technology for details.





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6.Dimensions

LGA6L Package





Symbol	Model	Sensor Area
A	TMR4M03BG	1.8
В	TMR4M02BG/04BG	2
С	TMR4M05BG	2.5
D	TMR4M08BG	4.5

Figure 5. Package outline of LGA6L (unit: mm)



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