

# SY89296U

2.5V/3.3V 1.5GHz Precision LVPECL Programmable Delay with Fine Tune Control

## Precision Edge<sup>®</sup>

### **General Description**

The SY89296U is a programmable delay line that delays the input signal using a digital control signal. The delay can vary from 3.2ns to 14.8ns in 10ps increments. Further, the delay may be varied continuously in about 40ps range by setting the voltage at the FTUNE pin. In addition, the input signal is LVPECL, uses either a 2.5V  $\pm$ 5% or 3.3V  $\pm$ 10% power supply, and is guaranteed over the full industrial temperature range (-40°C to +85°C).

The delay varies in discrete steps based on a control word. The control word is 10-bits long and controls the delay in 10ps increments. The eleventh bit is D[10] and is used to simultaneously cascade the SY89296U for a larger delay range. In addition, the input pins IN and /IN default to an equivalent low state when left floating. Further, for maximum flexibility, the control register interface accepts CMOS or TTL level signals.

For applications that do not require an analog delay input, see the SY89295U. The SY89295U and SY89296U are part of Micrel's high-speed, Precision Edge<sup>®</sup> product line.

Data sheets and support documentation can be found on Micrel's web site at: <u>www.micrel.com</u>.



#### Features

- Precision LVPECL programmable delay time
- Guaranteed AC performance over temperature and voltage:
  - $\qquad > 1.5 GHz \; f_{MAX}$
  - <160ps rise/fall times</p>
- Low jitter design:
  - <10ps<sub>PP</sub> total jitter
  - <2ps<sub>RMS</sub> cycle-to-cycle jitter
  - <1ps<sub>RMS</sub> random jitter
- Programmable delay range: 3.2ns to 14.8ns in 10ps increments
- Increased monotonicity over the MC100EP195
- ±10ps INL
- VBB output reference voltage
- Parallel inputs accept LVPECL or CMOS/LVTTL
- 40ps/V fine tune range
- Low voltage operation: 2.5V  $\pm 5\%$  and 3.3V  $\pm 10\%$
- Industrial -40°C to +85°C temperature range
- Available in 32-pin (5mm  $\times$  5mm) MLF  $^{\!\!8}$  package or 32-pin TQFP package

### Applications

- Clock de-skewing
- Timing adjustments
- Aperture centering

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# Ordering Information<sup>(1)</sup>

Part Number	Package Type	Operating Range	Package Marking	Lead Finish
SY89296UMI	MLF-32	-40°C to +85°C	SY89296U	Sn-Pb
SY89296UMITR <sup>(2)</sup>	MLF-32	-40°C to +85°C	SY89296U	Sn-Pb
SY89296UTI	T32-1	-40°C to +85°C	SY89296U	Sn-Pb
SY89296UTITR <sup>(2)</sup>	T32-1	-40°C to +85°C	SY89296U	Sn-Pb
SY89296UMG <sup>(3)</sup>	MLF-32	–40°C to +85°C	SY89296U with Pb-Free bar-line indicator	Pb-Free NiPdAu
SY89296UMGTR <sup>(2, 3)</sup>	MLF-32	–40°C to +85°C	SY89296U with Pb-Free bar-line indicator	Pb-Free NiPdAu
SY89296UTG <sup>(3)</sup>	T32-1	–40°C to +85°C	SY89296U with Pb-Free bar-line indicator	Pb-Free NiPdAu
SY89296UTGTR <sup>(2, 3)</sup>	T32-1	–40°C to +85°C	SY89296U with Pb-Free bar-line indicator	Pb-Free NiPdAu

#### Notes:

1. Contact factory for die availability. Dice are guaranteed at  $T_A = 25^{\circ}C$ , DC electricals only.

2. Tape and Reel.

3. Pb-Free package recommended for new designs.

## **Pin Configuration**



32-Pin MLF<sup>®</sup> (MLF-32)



32-Pin TQFP (T32-1)

## **Pin Description**

Pin Number	Pin Name	Pin Function				
23, 25, 26, 27, 29, 30, 31, 32, 1, 2	D[9:0]	"AC Electrical Characteristics" for delay value section which illustrates the proper interfacing D[9:0] contains pull-downs and defaults LOW	CMOS, ECL, or TTL Control Bits: These control signals adjust the delay from IN to Q. See "AC Electrical Characteristics" for delay values. In addition, see "Interface Applications" section which illustrates the proper interfacing techniques for different logic standards. D[9:0] contains pull-downs and defaults LOW when left floating. D0 (LSB), and D9 (MSB). See "Typical Operating Characteristics" for delay information.			
3	D10	delay range. In addition, it drives CASCADE	CMOS, ECL, or TTL Control Bit: This bit is used to cascade devices for an extended delay range. In addition, it drives CASCADE and /CASCADE. Further, D[10] contains a pull-down and defaults LOW when left floating.			
4, 5	IN, /IN	LVPECL/ECL Signal Input: Input signal to be will default to a logic LOW if left floating.	delayed. IN contains a $75 k\Omega$ pull-down and			
6	VBB <sup>(1)</sup>	Reference Voltage Output: When using a single-ended input signal source to IN or /IN, connect the unused input of the differential pair to this pin. This pin can also be used to rebias AC-coupled inputs to IN and /IN. When used, de-couple to Vcc using a $0.01\mu$ F capacitor, otherwise leave floating if not used. Maximum sink/source is ±0.5mA.				
7	VEF	Reference Voltage Output: Connect this pin t	o VcF when D[9:0], and D[10] is ECL.			
		Logic Standard	VCF Connects to:			
		LVPECL	VEF(1)			
		CMOS	No Connect			
		TTL	1.5V Source			
8	VCF	Reference Voltage Input: The voltage driven D[9:0], and D[10].	on VCF sets the logic transition threshold for			
9, 24, 28	GND, Exposed Pad <sup>(2)</sup>	Negative Supply: For MLF® package, expose that is the same potential as the ground pin.	ed pad must be connected to a ground plane			
10	LEN	ECL Control Input: When HIGH latches the D and D[10] latches are transparent.	0[9:0] and D[10] bits. When LOW, the D[9:0]			
11	SETMIN	ECL Control Input: When HIGH, D[9:0] regist SETMAX or D[9:0] and D[10]. SETMIN conta floating.	ers are reset. When LOW, the delay is set by ins a pull-down and defaults LOW when left			
12	SETMAX	ECL Control Input: When SETMAX is set HIC 1111111111. When SETMAX is LOW, the de SETMAX contains a pull-down and defaults I	elay is set by SETMIN or D[9:0] and D[10].			
13, 18, 19, 22	VCC	Positive Power Supply: Bypass with 0.1µF ar	nd 0.01µF low ESR capacitors.			
14, 15	/Cascade, Cascade	LVPECL Differential Output: The outputs are SY89296U to extend the delay range.	used when cascading two or more			
16	/EN	LVPECL Single-Ended Control Input: When I a differential LOW. /EN contains a pull-down	LVPECL Single-Ended Control Input: When LOW, Q is delayed from IN. When HIGH, Q is a differential LOW. /EN contains a pull-down and defaults LOW when left floating.			
20, 21	/Q, Q	LVPECL Differential Output: Q is a delayed v with $50\Omega$ to VCC – 2V. See "Output Interface				
17	FTUNE	Voltage Control Input: By varying the voltage "Propagation Delay vs. FTUNE Voltage." Lea				

Notes:

1. Single-ended operation is only functional at 3.3V.

2. MLF® package only.

# **Truth Tables**

#### Input/Output

Inputs		Output	s
IN	/IN	OUT	/OUT
0	1	0	1
1	0	1	0

## **Digital Control Latch**

LEN	Latch Action
0	Pass Through D[10:0]
1	Latched D[10:0]

#### Input Enable

/EN	Q, /Q
0	IN, /IN Delayed
1	Latched D[10:0]

## **Functional Block Diagram**



SY89296U Block Diagram

## Absolute Maximum Ratings<sup>(1)</sup>

Supply Voltage (V <sub>CC</sub> )	–0.5V to +4.0V
Input Voltage (V <sub>IN</sub> )	–0.5V to $V_{CC}$
LVPECL Output Current (I <sub>OUT</sub> )	
Continuous	50mA
Surge	100mA
Lead Temperature (soldering, 20sec.)	+260°C
Storage Temperature (T <sub>s</sub> )	65°C to +150°C

### **Operating Ratings**<sup>(2)</sup>

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Supply Voltage (V <sub>IN</sub> )	+2.375V to +3.6V
Ambient Temperature (T <sub>A</sub> )	40°C to +85°C
Package Thermal Resistance	
$MLF^{\mathbb{R}}(\theta_{JA})$	
Still-Air	35°C/W
$MLF^{\mathbb{R}}(\Psi_{JB})$	
Junction-to-Board	28°C/W
TQFP (θ <sub>JA</sub> )	
Still-Air	28°C/W
TQFP ( $\Psi_{JB}$ )	
Junction-to-Board	20°C/W

# DC Electrical Characteristics<sup>(4)</sup>

 $T_A = -40^{\circ}C$  to +85°C, unless otherwise stated.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
VCC	Power Supply	VCC = 2.5V	2.375	2.5	2.625	V
		VCC = 3.3V	3	3.3	3.6	v
IEE	Power Supply Current	No load, max. VCC			220	mA
VIN	Input Voltage Swing (IN, /IN)	See Figure 1a.	150		1200	mV
VDIFF_IN	Differential Input Voltage Swing (IN, /IN)	See Figure 1b.	300		2400	mV
VIHCMR	Input High Common Mode Range	IN, /IN	VEE + 1.2		VCC	V

$V_{CC} = 3.3V. T_{A}$	$= -40^{\circ}$ C to +85°C, unless other	wise stated.
••••••••••		

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
VIH	Input High Voltage (IN, /IN)		2.075		2.420	V
VIL	Input Low High Voltage (IN, /IN)		1.355		1.675	V
V <sub>BB</sub>	Output Voltage Reference		1.775	1.875	1.975	V
V <sub>EF</sub>	Mode Connection		1.9	2.0	2.1	V
V <sub>CF</sub>	Input Select Voltage		1.55	1.65	1.75	V

Notes:

1. Permanent device damage may occur if "Absolute Maximum Ratings" are exceeded. This is a stress rating only and functional operation is not implied at conditions other than those detailed in the operational sections of this data sheet. Exposure to "Absolute Maximum Rating" conditions for extended periods may affect device reliability.

2. The data sheet limits are not guaranteed if the device is operated beyond the operating ratings.

3. Thermal performance on MLF<sup>®</sup> packages assumes exposed pad is soldered (or equivalent) to the device most negative potential (GND).

4. The circuit is designed to meet the DC specifications shown in the table above after thermal equilibrium has been established. Input and output parameters vary 1:1 with  $V_{CC}$ , with the exception of  $V^{CF}$ .

# DC Electrical Characteristics<sup>(4)</sup> (Continued)

 $V_{CC}$  = 2.5V,  $T_A$  = –40°C to +85°C, unless otherwise stated.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
VIH	Input High Voltage (IN, /IN)		1.275		1.62	V
VIL	Input Low High Voltage (IN, /IN)		0.555		0.875	V
V <sub>BB</sub>	Output Voltage Reference		0.925	1.075	1.175	V
$V_{\text{EF}}$	Mode Connection		1.10	1.20	1.30	V
$V_{CF}$	Input Select Voltage		1.15	1.25	1.35	V

# LVPECL Outputs DC Electrical Characteristics<sup>(5)</sup>

 $V_{CC}$  = 3.3V,  $T_{A}$  = –40°C to +85°C;  $R_{LOAD}$  = 500 $\Omega$  to  $V_{CC}$  – 2V, unless noted.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
V <sub>OH</sub>	Output HIGH Voltage (Q, /Q)		2.155	2.280	2.405	V
V <sub>OL</sub>	Output LOW Voltage (Q, /Q)		1.355	1.480	1.605	V
V <sub>OUT</sub>	Output Voltage Swing (Q, /Q)	See Figure 1a.	550	800		mV
V <sub>DIFF_OUT</sub>	Differential Output Voltage Swing (Q, /Q)	See Figure 1b.	1.1	1.6		V

#### $V_{CC}$ = 2.5V, $T_{A}$ = –40°C to +85°C; $R_{LOAD}$ = 50 $\Omega$ to $V_{CC}$ – 2V, unless noted.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
V <sub>OH</sub>	Output HIGH Voltage (Q, /Q)		1.355	1.48	1.605	V
V <sub>OL</sub>	Output LOW Voltage (Q, /Q)		0.555	0.680	0.805	V
V <sub>OUT</sub>	Output Voltage Swing (Q, /Q)	See Figure 1a.	550	800		mV
V <sub>DIFF_OUT</sub>	Differential Output Voltage Swing (Q, /Q)	See Figure 1b.	1.1	1.6		V

## LVTTL/CMOS Outputs DC Electrical Characteristics<sup>(6)</sup>

 $V_{CC}$  = 2.5V  $\pm 5\%$  or 3.3V  $\pm 10\%;$   $T_{A}$  = –40°C to +85°C; unless noted.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
VCC	Power Supply	VCC = 2.5V	2.375	2.5	2.625	V
VCC		VCC = 3.3V	3	3.3	3.6	
IEE	Power Supply Current	No load, max. VCC			220	mA
VIN	Input Voltage Swing (IN, /IN)	See Figure 1a.	150		1200	mV
VDIFF_IN	Differential Input Voltage Swing (IN, /IN)	See Figure 1b.	300		2400	mV

Notes:

5. The circuit is designed to meet the DC specifications shown in the table above after thermal equilibrium has been established.  $V_{OH}$  and  $V_{OL}$  parameters vary 1:1 with  $V_{CC}$ .

6. The circuit is designed to meet the DC specifications shown in the table above after thermal equilibrium has been established

# AC Electrical Characteristics<sup>(7)</sup>

 $T_A = -40^{\circ}C$  to +85°C, unless otherwise stated.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
f <sub>MAX</sub>	Maximum Operating Frequency	Clock	1.5			GHz
t <sub>PD</sub>	Propagation Delay					
	IN to Q; D[0–10]=0		3200		4200	
	IN to Q; D[0–10]=1023		11500		14800	ne
	/EN to Q: D[0–10]=0		3400		4400	ps
	D10 to CASCADE		350		670	
t	Programmable Range					
t <sub>RANGE</sub>	t <sub>pd</sub> (max.) – t <sub>pd</sub> (min.)		8300			ps
+	Duty Cycle Skew					
tskew	t <sub>PHL</sub> — t <sub>PLH</sub>	Note 8			25	ps
	Step Delay					
	D0 High			10		
	D1 High			15		
	D2 High			35		
	D3 High			70		
Δt	D4 High			145		ps
Δι	D5 High			290		μs
	D6 High			575		
	D7 High			1150		
	D8 High			2300		
	D9 High			4610		
	D0 – D9 High			9220		
INL	Integral Non-Linearity	Note 9		±10		ps

#### Notes:

7. High-frequency AC electricals are guaranteed by design and characterization.

8. Duty cycle skew guaranteed only for differential operation measured from the crosspoint of the input to the crosspoint of the output.

INL (Integral Non-Linearity) is defined from its corresponding point on the ideal delay vs. D[9:0] curve as the deviation from its ideal delay. The maximum difference is the INL. Theoretical Ideal Linearity (TIL) = measured maximum delay – measured minimum delay) ÷ 1024. INL = measured delay – measured minimum delay + (step number × TIL).

# AC Electrical Characteristics<sup>(7)</sup> (Continued)

 $T_{\text{A}}$  = –40°C to +85°C, unless otherwise stated.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units	
ts	Set-Up Time						
	D t+o LEN	Note 10	200			<b>n</b> 0	
	D to IN	Note 11	350			ps	
	/EN to IN		300				
	Hold Time						
t <sub>H</sub>	LEN to D		200			ps	
	IN to /EN	Note 12	400				
	Release Time						
•	/EN to IN		500			<b>n</b> 0	
t <sub>R</sub>	SETMAX to LEN		500			- ps	
	SETMIN to LEN		450				
	Cycle-to-Cycle Jitter	Note 13			2	ps <sub>RMS</sub>	
<b>t</b> <sub>JITTER</sub>	Total Jitter	Note 14			10	ps <sub>PP</sub>	
	Random Jitter	Note 15			1	ps <sub>RMS</sub>	
t <sub>r</sub> , t <sub>f</sub>		20% to 80% (Q)	50	85	160	ps	
	Output Rise/Fall Time	20% to 80% (CASCADE)	90		300	ps	
	Duty Cycle		45		55	%	
f <sub>T</sub>	FTUNE	$0 \le F_{TUNE} \le 1.25V$		47	52	Ps/V	

#### Notes:

10. This setup time defines the amount of time prior to the input signal. The delay tap of the device must be set.

11. This setup time defines the amount of the time that /EN must be asserted prior to the next transition of IN, /IN to prevent an output response greater than ±75mV to the IN, /IN transition.

12. Hold time is the minimum time that /EN must remain asserted after a negative going IN or a positive going /IN to prevent an output response greater than ±75mV to that IN, /IN transition .

13. Cycle-to-cycle jitter definition: the variation of periods between adjacent cycles over a random sample of adjacent cycle pairs  $T_{jitter_{cc}} = T_n - T_n + 1$ , where T is the time between rising edges of the output signal.

14. Total jitter definition: with an ideal clock input, no more than one output edge in 10<sup>12</sup> output edges will deviate by more than the specified peak-topeak jitter value.

15. Random jitter definition: jitter that is characterized by a Gaussian distribution, unbounded and is quantified by its standard deviation and mean. Random jitter is measured with a K28.7 comma defect pattern, measured at 1.5Gbps.

## **Typical Operating Characteristics**

 $V_{CC}$  = 3.3V, GND = 0,  $D_{IN}$  = 100mV,  $T_A$  = 25°C, unless otherwise noted.



## **Timing Diagram**



## Single-Ended and Differential Swings



Figure 1a. Single-Ended Voltage Swing



Figure 1b. Differential Voltage Swing

## Input and Output Stages











Figure 3. LVPECL Output Stage

### **Output Interface Applications**



#### Figure 4. Parallel Termination







## **Application Information**

For best performance, use good high frequency layout techniques, filter  $V_{CC}$  supplies, and keep ground connections short. Use multiple vias where possible. Also, use controlled impedance transmission lines to interface with the SY89296U data inputs and outputs.

#### V<sub>BB</sub> Reference

The VBB pin is an internally generated reference and is available for use only by the SY89296U. When unused, this pin should be left unconnected. The two common uses for  $V_{BB}$  are to handle a single-ended PECL input, and to re-bias inputs for AC-coupling applications.

If either IN or /IN is driven by a single-ended output,  $V_{BB}$  is used to bias the unused input. Please refer to Figure 10. The PECL signal driving the SY89296U may optionally be inverted in this case.

When the signal is AC-coupled,  $V_{BB}$  is used, as shown in Figure 13, to re-bias IN and/or /IN. This ensures that SY89296U inputs are within acceptable common mode range.

In all cases,  $V_{\text{BB}}$  current sinking or sourcing must be limited to 0.5mA or less.

#### Setting D Input Logic Thresholds

In all designs where the SY89296U GND supply is at zero volts, the D inputs can accommodate CMOS and TTL level signals, as well as PECL or LVPECL. Figures 11, 12, and 14 show how to connect VCF and VEF for all possible cases.

#### Cascading

Two or more SY89296U may be cascaded in order to extend the range of delays permitted. Each additional SY89296U adds about 3.2ns to the minimum delay and adds another 10240ps to the delay range.

Internal cascade circuitry has been included in the SY89296U. Using this internal circuitry, the SY89296U may be cascaded without any external gating.

Examples of cascading 2, 3, or 4 SY89296U appear in Figures 7, 8, and 9.







Figure 8. Cascading Three SY89296U



Figure 9. Cascading Four SY896296U

## **Interface Applications**

LVPECL INPUT\*











Figure 13. Re-Biasing an AC-Coupled Signal



Figure 11.  $V_{CF}$  /  $V_{EF}$  Biasing for LVPECL Control (D) Input



Figure 14. V<sub>CF</sub> / V<sub>EF</sub> Biasing for LVTTL Control (D) Input

## **Related Product and Support Documentation**

Part Number	Function	Data Sheet Link
SY89295U2.5/3.3V 1.5GHz Precision LVPECL Programmable Delay		www.micrel.com/product-info/products/sy89295u.shtml
SY89296U	2.5/3.3V 1.5GHz Precision LVPECL Programmable Delay with Fine Tune Control	www.micrel.com/product-info/products/sy89296u.shtml
	16-MLF <sup>®</sup> Manufacturing Guidelines Exposed Pad Application Note	www.amkor.com/products/notes papers/MLF appnote 0902.pdf
	HBW Solutions	www.micrel.com/product-info/as/solutions.shtml

### **Package Information**



- 1. Package meets Level 2 qualification.
- 2. All parts are dry-packaged before shipment.
- 3. Exposed pads must be soldered to a ground for proper thermal management.



## Package Information (Continued)



32-Pin TQFP (T32-1)

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