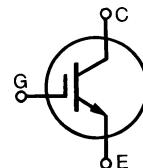


# Ultra-Low $V_{CE(sat)}$ IGBT

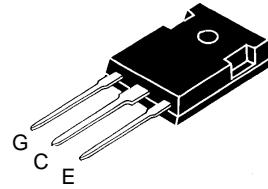
# IXGH 38N60

$V_{CES}$  = 600 V  
 $I_{C25}$  = 76 A  
 $V_{CE(sat)}$  = 1.8 V



Symbol	Test Conditions	Maximum Ratings		
$V_{CES}$	$T_J$ = 25°C to 150°C	600	V	
$V_{CGR}$	$T_J$ = 25°C to 150°C; $R_{GE}$ = 1 MΩ	600	V	
$V_{GES}$	Continuous	±20	V	
$V_{GEM}$	Transient	±30	V	
$I_{C25}$	$T_C$ = 25°C	76	A	
$I_{C90}$	$T_C$ = 90°C	38	A	
$I_{CM}$	$T_C$ = 25°C, 1 ms	152	A	
<b>SSOA (RBSOA)</b>	$V_{GE} = 15$ V, $T_{VJ} = 125^\circ\text{C}$ , $R_G = 10$ Ω Clamped inductive load, $L = 100$ μH	$I_{CM} = 76$ @ 0.8 $V_{CES}$	A	
$P_c$	$T_C$ = 25°C	200	W	
$T_J$		-55 ... +150	°C	
$T_{JM}$		150	°C	
$T_{stg}$		-55 ... +150	°C	
$M_d$	Mounting torque (M3)	1.13/10	Nm/lb.in.	
<b>Weight</b>		6	g	
Maximum lead temperature for soldering 1.6 mm (0.062 in.) from case for 10 s		300	°C	

TO-247 AD



G = Gate,  
E = Emitter,  
C = Collector,  
TAB = Collector

## Features

- International standard package JEDEC TO-247 AD
- 2nd generation HDMOS™ process
- Low  $V_{CE(sat)}$ 
  - for minimum on-state conduction losses
- High current handling capability
- MOS Gate turn-on
  - drive simplicity

## Applications

- AC motor speed control
- DC servo and robot drives
- DC choppers
- Uninterruptible power supplies (UPS)
- Switch-mode and resonant-mode power supplies

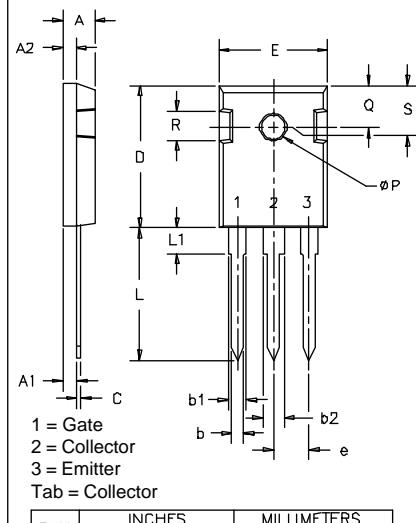
## Advantages

- Easy to mount with 1 screw (isolated mounting screw hole)
- Low losses, high efficiency
- High power density

Symbol	Test Conditions	Characteristic Values		
		( $T_J$ = 25°C, unless otherwise specified)	min.	typ.
$BV_{CES}$	$I_C$ = 250 μA, $V_{GE} = 0$ V	600		V
$V_{GE(th)}$	$I_C$ = 250 μA, $V_{CE} = V_{GE}$	2.5		V
$I_{CES}$	$V_{CE} = 0.8 \cdot V_{CES}$ $V_{GE} = 0$ V	$T_J = 25^\circ\text{C}$ $T_J = 125^\circ\text{C}$		200 μA 1 mA
$I_{GES}$	$V_{CE} = 0$ V, $V_{GE} = \pm 20$ V			±100 nA
$V_{CE(sat)}$	$I_C = I_{C90}$ , $V_{GE} = 15$ V			1.8 V

Symbol	Test Conditions	Characteristic Values		
		min.	typ.	max.
$g_{fs}$	$I_c = I_{C90}; V_{CE} = 10 \text{ V},$ Pulse test, $t \leq 300 \mu\text{s}$ , duty cycle $\leq 2 \%$	15	20	S
$C_{ies}$ $C_{oes}$ $C_{res}$	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$	2500	pF	
		230	pF	
		70	pF	
$Q_g$ $Q_{ge}$ $Q_{gc}$	$I_c = I_{C90}, V_{GE} = 15 \text{ V}, V_{CE} = 0.5 V_{CES}$	125	150	nC
		23	35	nC
		50	75	nC
$t_{d(on)}$ $t_{ri}$ $t_{d(off)}$ $t_{fi}$ $E_{off}$	Inductive load, $T_J = 25^\circ\text{C}$  $I_c = I_{C90}, V_{GE} = 15 \text{ V}, L = 100 \mu\text{H}$ $V_{CE} = 0.8 V_{CES}, R_G = R_{off} = 10 \Omega$  Remarks: Switching times may increase for $V_{CE}$ (Clamp) $> 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$	30		ns
		150		ns
		600	1200	ns
		500	700	ns
		9	15	mJ
$t_{d(on)}$ $t_{ri}$ $E_{on}$ $t_{d(off)}$ $t_{fi}$ $E_{off}$	Inductive load, $T_J = 125^\circ\text{C}$  $I_c = I_{C90}, V_{GE} = 15 \text{ V}, L = 100 \mu\text{H}$ $V_{CE} = 0.8 V_{CES}, R_G = R_{off} = 10 \Omega$  Remarks: Switching times may increase for $V_{CE}$ (Clamp) $> 0.8 \cdot V_{CES}$ , higher $T_J$ or increased $R_G$	40		ns
		160		ns
		1		mJ
		800		ns
		1000		ns
$R_{thJC}$			0.62	K/W
$R_{thICK}$		0.25		K/W

TO-247 AD Outline



SYM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	.185	.209	4.7	5.3
A <sub>1</sub>	.087	.102	2.2	2.54
A <sub>2</sub>	.059	.098	2.2	2.6
b	.040	.055	1.0	1.4
b <sub>1</sub>	.065	.084	1.65	2.13
b <sub>2</sub>	.113	.123	2.87	3.12
C	.016	.031	.4	.8
D	.819	.845	20.80	21.46
E	.610	.640	15.75	16.26
e	.215	BSC	5.45	BSC
L	.780	.800	19.81	20.32
L <sub>1</sub>		.177		4.50
ØP	.140	.144	3.55	3.65
Q	.212	.244	5.4	6.2
R	.170	.216	4.32	5.49
S	.242	BSC	6.15	BSC