

# SHT4xI-Digital

4<sup>th</sup> Generation, High-Accuracy, 16-bit, Industrial-Grade, Relative Humidity and Temperature Sensor



# Features

- Accuracies  $\Delta RH = \pm 2.0$  %RH,  $\Delta T = \pm 0.2$  °C
- Supply voltage VDD = 2.3 V...5.5 V
- Average current: 21 μA (at meas. rate 1 Hz)
- I2C fast mode plus, CRC checksum
- Operating range: 0...100 %RH, -40...125 °C
- Variable power heater

- Fully functional in condensing environment
- Reliable water activity measurement in oil
- NIST traceability
- Mature technology from global market leader
- JEDEC JESD47 qualification, high ESD protec.
- Patented protection options

# **General Description**

SHT4xI-Digital is an industrial-grade digital sensor platform for measuring relative humidity and temperature with different accuracy classes. It meets demanding ESD and robustness requirements of industrial applications. The sensors can be interfaced via several preconfigured I2C addresses. An integrated heater allows for advanced on-board-diagnostics while the sensor element is designed for harsh conditions such as condensing environments. The four-pin dual-flat-no-leads package is suitable for surface mount technology (SMT) processing. Protection options such as patented filter membranes and protective covers, available for any member of the SHT4xI-Digital family, enable operation in harshest environments and advanced production processes.

# **Device Overview**

| Products    | Details                              |
|-------------|--------------------------------------|
| SHT40I-AD1B | base RH&T accur., 0x44 I2C addr.     |
| SHT40I-AD1F | SHT40I-AD1B with PTFE membrane       |
| SHT41I-AD1B | improved RH&T accur., 0x44 I2C addr. |
| SHT41I-AD1F | SHT41I-AD1B with PTFE membrane       |

Full product list on page 17.



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# **Functional Block Diagram**



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# 1 Quick Start – Hello World

A typical application circuit for SHT4xl-Digital is shown on the left-hand side of **Figure 1**. After reaching the minimal supply voltage and allowing for the maximal power-up time of 1 ms the sensor is ready for I2C communication. The quickest way to measure humidity and temperature is pseudo-coded on the right-hand side of **Figure 1**. Together with the conversion formulae given in equations (1), (3), (3), and (4), the digital signals can be translated into relative humidity and temperature readings.



**Figure 1.** Typical application circuit (left) and pseudo code (right) for easy starting. For details on the signal cropping in the last four lines see section 4.6.

Find code resources and embedded drivers on: https://github.com/Sensirion/embedded-sht/releases



CAD files can be downloaded from SnapEDA: https://www.snapeda.com/search/?q=sht4%3FI-&search-type=parts



# 2 Humidity and Temperature Sensor Specifications

Every SHT4xI-Digital is individually tested and calibrated and is identifiable by its unique serial number (see section 4.7 for details on the serial number). For the calibration, Sensirion uses transfer standards, which are subject to a scheduled calibration procedure. The calibration of the reference, used for the calibration of the transfer standards, is NIST traceable through an ISO/IEC 17025 accredited laboratory.

#### 2.1 Relative Humidity

| Parameter                                      | Conditions | Value        | Units |
|--|------------|--------------|-------|
| SHT40I-Digital <i>RH</i> accuracy <sup>1</sup> | typ.       | ±2           | %RH   |
| SH1401-Digital KH accuracy                     | max.       | see Figure 2 | -     |
| SHT41I-Digital <i>RH</i> accuracy <sup>1</sup> | typ.       | ±2           | %RH   |
| SHT4TI-Digital KH accuracy                     | max.       | see Figure 3 | -     |
|  | high       | 0.08         | %RH   |
| Repeatability <sup>2</sup>                     | medium     | 0.15         | %RH   |
|  | low        | 0.21         | %RH   |
| Resolution <sup>3</sup>                        | -          | 0.01         | %RH   |
| Hysteresis                                     | At 25 °C   | ±0.8         | %RH   |
| Specified range <sup>4</sup>                   | extended⁵  | 0 to 100     | %RH   |
| Response time <sup>6</sup>                     | T63%       | 4            | S     |
| Long-term drift <sup>7</sup>                   | typ.       | <0.2         | %RH/y |

Table 1. General relative humidity sensor specifications.



**Figure 2.** SHT40I-Digital typical and maximal relative humidity accuracy at 25 °C.



**Figure 3.** SHT41I-Digital typical and maximal relative humidity accuracy at 25 °C.

<sup>&</sup>lt;sup>1</sup> For definition of typ. and max. accuracy, please refer to the document "Sensirion Humidity Sensor Specification Statement".

<sup>&</sup>lt;sup>2</sup> The stated repeatability is three times the standard deviation (3σ) of multiple consecutive measurement values at constant conditions and is a measure for the noise on the physical sensor output. Different repeatability commands are listed in **Table 8**.

<sup>&</sup>lt;sup>3</sup> Resolution of A/D converter.

<sup>&</sup>lt;sup>4</sup> Specified range refers to the range for which the humidity or temperature sensor specification is guaranteed.

<sup>&</sup>lt;sup>5</sup> For details about recommended humidity and temperature operating range, please refer to section 2.3.

<sup>&</sup>lt;sup>6</sup> Time for achieving 63% of a humidity step function, measured at 25 °C and 1 m/s airflow. Humidity response time in the application depends on the design-in of the sensor.

<sup>&</sup>lt;sup>7</sup> Typical value for operation in normal RH/T operating range. Value may be higher in environments with vaporized solvents, out-gassing tapes, adhesives, packaging materials, etc. For more details, please refer to the Handling Instructions [1]

### 2.2 Temperature

| Parameter                                     | Conditions   | Value        | Units |
|---|--------------|--------------|-------|
| SHT40I-Digital <i>T</i> Accuracy <sup>1</sup> | typ.         | ±0.2         | °C    |
| Sift 401-Digital 7 Accuracy                   | max.         | see Figure 4 | -     |
| SHT41 Digital TAcouroou                       | typ.         | ±0.2         | °C    |
| SHT41I-Digital <i>T</i> Accuracy <sup>1</sup> | max.         | see Figure 5 | -     |
|   | high         | 0.04         | °C    |
| Repeatability <sup>2</sup>                    | medium       | 0.07         | °C    |
|   | low          | 0.1          | °C    |
| Resolution <sup>3</sup>                       | -            | 0.01         | °C    |
| Specified range <sup>4</sup>                  | -            | -40 to +125  | °C    |
| Response time <sup>8</sup>                    | $	au_{63\%}$ | 2            | S     |
| Long-term drift <sup>9</sup>                  | typ.         | <0.03        | °C/y  |

Table 2. General temperature sensor specifications.



**Figure 4.** SHT40I-Digital typical and maximal temperature accuracy.



**Figure 5.** SHT41I-Digital typical and maximal temperature accuracy.

### 2.3 Recommended Operating Conditions

The sensor shows best performance when operated within the recommended normal temperature and humidity range of 5 °C...60 °C and 20 %RH ... 80 %RH, respectively. Long term exposure to conditions outside recommended normal range, especially at high relative humidity, may temporarily offset the RH signal (*e.g.* +3 %RH after 60 h at >80 %RH). After returning into the recommended temperature and humidity range the sensor will recover to within specifications by itself. Prolonged exposure to extreme conditions may accelerate ageing.

To ensure stable operation of the humidity sensor, the conditions described in the Handling Instruction [1] regarding exposure to volatile organic compounds must be met. Please note as well that this does apply not only to transportation and manufacturing, but also to operation of the SHT4xI-Digital.

<sup>&</sup>lt;sup>8</sup> Temperature response time depends on heat conductivity of sensor substrate and design-in of sensor in application.

<sup>&</sup>lt;sup>9</sup> Max. value is <0.04 °C/y.



#### 2.4 Water Activity in Oil

Increased water activity in an oil indicates advanced aging and quality loss. Being able to retrieve data on the water activity in the oil, allows conclusions to be drawn about the degree of degradation of an oil, which strongly influences its properties, *e.g.* insulating ability Thus, in crucial processes relying on the flawless performance of an oil, an implemented online monitoring of an oils water activity, is very beneficial. For example, the occurrence of breakdowns caused by degraded, no longer insulating oil in electrical transformers, can be predicted, and consequently reduced.

Next to relative humidity measurements in air, the SHT4xI-digital<sup>10</sup> is suitable for water activity measurements in oil<sup>11</sup>. Similar to relative humidity, defined as the ratio of partial pressure of water in air and the saturation partial pressure, the water activity ( $a_w$ ) in oil is defined as the ratio of water in solution to the saturation water content at the corresponding temperature. Conventionally,  $a_w$  is indicated in values from 0 to 1 instead of percentages known from relative humidity in air. Therefore, the signal conversion formula for water activity measurements differs from the RH conversion formula, as described in section 4.6. Other than that, no additional adaptions compared to the measurement in air are required. Specifications<sup>12</sup> for the use in mineral transformer oils can be found in **Table 3** below.

| Parameter                           | Conditions | Value  | Units             |
|-------------------------------------|------------|--------|-------------------|
| SHT4xI-Digital $a_{\rm w}$ accuracy | typ.       | ±0.02  | $a_{\mathrm{w}}$  |
| Resolution <sup>13</sup>            | -          | 0.0001 | a <sub>w</sub>    |
| Specified $a_{\rm w}$ range         | -          | 0 to 1 | a <sub>w</sub>    |
| Long-term drift <sup>14</sup>       | max.       | 0.005  | a <sub>w</sub> /y |

 Table 3. Water activity measurement specifications from 15 °C to 60 °C

As differences in oil compositions strongly affect water absorption and diffusion kinetics, and thus the response time during water activity measurements, the response time of the sensor strongly depends on the used oil and cannot be specified generally. Please note, that due to the slow kinetics of water diffusion in oil, placement of the sensor, homogeneity, and potentially mixing conditions, are of utmost importance to obtain correct measurements with any sensor.

<sup>&</sup>lt;sup>10</sup> Excluding version with PTFE membrane

<sup>&</sup>lt;sup>11</sup> In general a<sub>w</sub> is independent of the oil being measured and works regardless of its chemical composition. Nevertheless, careful evaluation of oils is recommended since additives, or some oil components could falsify the measurements or harm the sensor. Furthermore, the sensors should only be used it in

recommended since additives, or some oil components could falsify the measurements or harm the sensor. Furthermore, the sensors should only be used it in oils with low electrical conductivity.

<sup>&</sup>lt;sup>12</sup> Specified only for temperature range from 15 °C to 60 °C, as determined for J10 transformer oil (DIN 57370 – VDE 0370).

<sup>&</sup>lt;sup>13</sup> Resolution of A/D converter

<sup>&</sup>lt;sup>14</sup>Typical value for operation in normal a<sub>w</sub> operating range in mineral oils. Value may be higher in environments with higher additive concentration.



# **3 Electrical Specifications**

Valid for all electrical specifications: Typical values correspond to  $V_{DD} = 3.3$  V and T = 25 °C. Min. and max. values are valid in the full temperature range -40 °C ... 125 °C, at declared  $V_{DD}$  levels and are based on characterization.

## **3.1 Electrical Characteristics**

| Parameter                           | Sym<br>bol             | Conditions  | Min              | Тур. | Max              | Unit<br>s | Comments  |
|-------------------------------------|------------------------|---|------------------|------|------------------|-----------|---|
| Supply voltage                      | Vdd                    |   | 2.3              | 3.3  | 5.5              | V         | -   |
| Power-up/down<br>level              | VPOR                   | Static power supply   | 0.7              | -    | 2.3              | V         | -   |
|                                     |                        | Idle state  | -                | 18   | -                | μA        | -   |
| Supply current (heater <b>off</b> ) | <b>I</b> DD            | Measurement   | -                | 350  | -                | μA        | Average current<br>consumption while<br>sensor is measuring   |
|                                     |                        | Aver., high repeatab.   | -                | 21   | -                |           | Aver. current   |
|                                     |                        | Aver., med repeatab.  | -                | 19   | -                | μA        | consumpt. (contin.  |
|                                     |                        | Aver., low repeatab.  | -                | 18   | -                |           | operation at 1Hz)   |
| Supply current                      |                        | Nomin. heater "200mW"   | -                | 40   | 80               | mA        |   |
| (heater <b>on</b> )                 | <b>I</b> dd            | Nomin. heater "110mW"   | -                | 22   | 44               | mΑ        | see section 4.9   |
|                                     |                        | Nomin. heater "20mW"  | -                | 4    | 8                | mΑ        |   |
| Low level input voltage             | VIL                    | -   | 0                | -    | 0.3* <i>V</i> dd | V         | -   |
| High level input voltage            | Vін                    | -   | 0.7* <i>V</i> DD | -    | V <sub>DD</sub>  | V         | -   |
|                                     | Rp                     | $V_{\rm DD} < 3.0 \ { m V}$   | 820              | -    | -                | - Ω -     |   |
| Pull up resistors                   |                        | <i>V</i> <sub>DD</sub> ≥ 3.0 V  | 390              |      |                  | Ω         | -   |
| Low level output                    | Vol                    | $V_{\text{DD}} \ge 2.3 \text{ V}, R_{\text{p}} \ge 820 \Omega$                      | _                | _    | 0.4              | V         | _   |
| voltage                             | VOL                    | $V_{\text{DD}} \ge 3.0 \text{ V}, R_{\text{p}} \ge 390 \Omega$                      | -                | -    | 0.4              | v         | -   |
|                                     | us load C <sub>b</sub> | $R_{\rm p} \ge 820 \ \Omega$ : fast mode  | -                | -    | 400              | pF        | Capac. bus load can<br>be determined from<br><i>C</i> <sub>b</sub> < <i>t</i> <sub>rise</sub>   |
| Cap bus load                        |                        | $R_{\rm p} \ge 390 \ \Omega,$<br>$V_{\rm DD} \ge 3.0 \ {\rm V}$ : fast mode<br>plus | -                | -    | 340              | pF        | /(0.8473*R <sub>p</sub> ).<br>Rise times are<br>$t_{rise}$ = 300 ns for fast<br>mode and<br>$t_{rise}$ = 120 ns for fast<br>mode plus |

 Table 4. Electrical specifications.



## 3.2 Timings

| Parameter               | Symbol                           | Conditions  | Min. | Тур. | Max. | Units | Comments  |  |
|-------------------------|----------------------------------|---|------|------|------|-------|---|--|
| Power-up time           | <b>t</b> ₽U                      | After hard reset,<br>V <sub>DD</sub> ≥ V <sub>POR</sub> | -    | 0.3  | 1    | ms    | Time between V <sub>DD</sub><br>reaching V <sub>POR</sub> and<br>sensor entering idle<br>state                            |  |
| Soft reset time         | <i>t</i> sr                      | After soft reset  | -    | -    | 1    | ms    | Time between ACK of<br>soft reset command and<br>sensor entering idle<br>state. Also valid for I2C<br>general call reset. |  |
|                         | <b>t</b> MEAS,I                  | Low<br>repeatability                                    | -    | 1.3  | 1.6  | ms    | The three repeatability   |  |
| Measurement<br>duration | <b>t</b> MEAS,m                  | Med.<br>repeatability                                   | -    | 3.7  | 4.5  | ms    | modes differ with<br>respect to measurement<br>duration, noise level and  |  |
|                         | <b>ⅈ</b> MEAS,h                  | High<br>repeatability                                   | -    | 6.9  | 8.3  | ms    | energy consumption  |  |
| Heater on duration      | -on duration t <sub>Heater</sub> | Long pulse  | 0.81 | 1    | 1.19 | s     | After that time, the heater is automatically switched off   |  |
| Heater-on duration      |                                  | Short pulse   | 0.08 | 0.1  | 0.12 | s     | After that time, the heater is automatically switched off   |  |

 Table 5. System timing specifications.

### 3.3 Absolute Maximum Ratings

Stress levels beyond those listed in **Table 6** may cause permanent damage or affect the reliability of the device. These are stress ratings only and functional operation of the device at these conditions is not guaranteed. Ratings are only tested each at a time.

| Parameter                               | Rating   |
|---|--|
| Supply voltage VDD                      | -0.3 V6.0 V                                    |
| Max. voltage on any pin                 | V <sub>SS</sub> -0.3 V V <sub>DD</sub> + 0.3 V |
| Operating temperature range             | −40 °C…125 °C                                  |
| Storage temperature range <sup>15</sup> | −40 °C…150 °C                                  |
| ESD HBM                                 | 4 kV   |
| ESD CDM                                 | 750 V  |
| Latch up, JESD78 Class II, 125 °C       | ±100 mA  |

**Table 6.** Absolute maximum ratings.

# **4 Sensor Operation**

## 4.1 I2C Communication

I2C communication is based on NXP's I2C-bus specification and user manual UM10204, Rev.6, 4 April 2014. Supported I2C modes are standard, fast mode, and fast mode plus. Data is transferred in multiples of 16-bit words and 8-bit check sum (cyclic redundancy check = CRC). All transfers must begin with a start condition (S) and terminate with a stop condition (P). To finish a read transfer, send not acknowledge (NACK) and stop condition (P). Addressing a specific slave device is done by sending its 7-bit I2C address followed by an eighth bit, denoting the communication

<sup>&</sup>lt;sup>15</sup> The recommended storage temperature range is 10-50 °C. Please refer to the Handling Instructions [1] for more information.

direction: "zero" indicates transmission to the slave, i.e. "write", a "one" indicates a "read" request. Schematics of the I2C transfer types are sketched in **Figure 6**. The sensor does not support clockstretching. In case the sensor receives a read header and is still busy with *e.g.* measurement or heating, it will return a NACK. Measurement data can only be received once and will be deleted from the sensor's register after the first acknowledged I2C read header.



**Figure 6.** I2C transfer types: First a write header is sent to the I2C slave, followed by a command, for example "measure RH&T with highest precision". After the measurement is finished the read request directed to this I2C slave will be acknowledged and transmission of data will be started by the slave (here, only the temperature values are transmitted for reasons of simplicity).

#### 4.2 I2C Communication Timing

All details on the timing are following the interface specification of NXP's user manual UM10204, Rev.6, 4 April 2014. Please follow mandatory capacitor and resistor requirements given in **Table 4**.

## 4.3 Data Type & Length

I2C bus operates with 8-bit data packages. Information from the sensor to the master has a checksum after every second 8-bit data package.

Humidity and temperature data will always be transmitted in the following way: The first value is the temperature signal (2 \* 8-bit data + 8-bit CRC), the second is the humidity signal (2 \* 8-bit data + 8-bit CRC).

### 4.4 Checksum Calculation

For read transfers each 16-bit data is followed by a checksum with the following properties

| Property             | Value                        |
|----------------------|------------------------------|
| Name                 | CRC-8                        |
| Message Length       | 16-bit                       |
| Polynomial           | $0x31 (x^8 + x^5 + x^4 + 1)$ |
| Initialization       | 0xFF                         |
| Reflect Input/Output | false/false                  |
| Final XOR            | 0x00                         |
| Examples             | CRC(0xBEEF) = 0x92           |

**Table 7.** Data check sum properties.

The master may abort a read transfer after the 16-bit data if it does not require a checksum.



## 4.5 Command Overview

| Command<br>(hex) | Response length incl. CRC (bytes) | Description<br>[return values]  |
|------------------|-----------------------------------|---|
| 0xFD             | 6                                 | measure T & RH with high precision (high repeatability)<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]  |
| 0xF6             | 6                                 | measure T & RH with medium precision (medium repeatability)<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]  |
| 0×E0             | 6                                 | measure T & RH with lowest precision (low repeatability)<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]   |
| 0x89             | 6                                 | read serial number<br>[2 * 8-bit data; 8-bit CRC; 2 * 8-bit data; 8-bit CRC]  |
| 0x94             | -                                 | soft reset<br>[ACK]   |
| 0x39             | 6                                 | activate heater with 200 mW for 1 s, including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]  |
| 0x32             | 6                                 | activate heater with 200 mW for 0.1 s including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC] |
| 0x2F             | 6                                 | activate heater with 110 mW for 1 s including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]   |
| 0x24             | 6                                 | activate heater with 110 mW for 0.1 s including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC] |
| 0x1E             | 6                                 | activate heater with 20 mW for 1 s including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]    |
| 0x15             | 6                                 | activate heater with 20 mW for 0.1 s including a high precision<br>measurement just before deactivation<br>[2 * 8-bit T-data; 8-bit CRC; 2 * 8-bit RH-data; 8-bit CRC]  |

**Table 8.** Overview of I2C commands. If the sensor is not ready to process a command, *e.g.* because it is still measuring, it will response with NACK to the I2C read header. Given heater power values are typical and valid for VDD = 5.0 V.

## 4.6 Conversion of Signal Output

The digital sensor signals correspond to following humidity, water activity, and temperature values:

$$RH = \left(-6 + 125 \cdot \frac{S_{RH}}{2^{16} - 1}\right) \% RH \tag{1}$$

$$a_w = \frac{1}{100} \left( -6 + 125 \cdot \frac{S_{RH}}{2^{16} - 1} \right) \tag{2}$$

$$T = \left(-45 + 175 \cdot \frac{S_T}{2^{16} - 1}\right) \circ C \tag{3}$$

$$T = \left(-49 + 315 \cdot \frac{S_T}{2^{16} - 1}\right) \,^{\circ} \mathrm{F} \tag{4}$$

N.B.: The RH conversion formula (1) allows values to be reported which are outside of the range of 0 %RH ... 100 %RH. Relative humidity values which are smaller than 0 %RH and larger than 100 %RH are non-physical, however these "uncropped" values might be found beneficial in some cases (*e.g.* when the distribution of the sensors at the measurement boundaries are of interest). For all users who do not want to engage in evaluation of these non-physical values, cropping of the RH signal to the range of 0 %RH ... 100 %RH is advised.



### 4.7 Serial Number

Every sensor has a unique serial number, that is assigned by Sensirion during production. It is stored in the one-time-programmable memory and cannot be manipulated after production. The serial number is accessible via I2C and is transmitted as two 16-bit words, each followed by an 8-bit CRC.

### 4.8 Reset

A reset of the sensor can be achieved in three ways:

- 1. Soft reset: send the reset command described in Table 8.
- 2. I2C general call: all devices on I2C bus are reset by sending the command 0x06 to the I2C address 0x00.
- 3. Power down (incl. pulling SCL and SDA low)

#### 4.9 Heater Operation

The sensor incorporates an integrated on-chip heater which can be switched on by the set of commands given in **Table 8**. There are three different heating powers and two different heating times accessible to the user. After reception of a heater-on command, the sensor executes the following procedure:

- 1. The heater is enabled, and the timer starts its count-down.
- 2. On timer expiration a temperature and humidity measurement with the highest repeatability is started, the heater remains enabled.
- 3. After the measurement is finished the heater is turned off.
- 4. Temperature and humidity values are now available.

The maximum on-time of the heater commands is one second to prevent overheating of the sensor by unintended usage of the heater. Thus, there is no dedicated command to turn off the heater. For extended heating periods it is required to send periodic heater-on commands, keeping in mind that the heater is designed for a maximal duty cycle of less than 10%. To obtain a fast increase in temperature the idle time between consecutive heating pulses shall be kept minimal.

#### Possible Heater Use Cases

There will be dedicated Sensirion application notes elaborating on various use cases of the heater. In general, the applications of the on-chip heater range around:

- 1. Removal of condensed / spray water on the sensor surface. Although condensed water is not a reliability / quality problem to the sensor, it will however make the sensor non-responsive to RH changes in the air as long as there is liquid water on the surface.
- 2. Creep-free operation in high humid environments. Periodic heating pulses allow for creepfree high-humidity measurements for extended times.

### Important notes for operating the heater:

- 1. The heater is designed for a maximum duty cycle of 10%, meaning the total heater-ontime should not be longer than 10% of the sensor's lifetime.
- 2. During operation of the heater, sensor specifications are not valid.
- 3. The temperature sensor can additionally be affected by the thermally induced mechanical stress, offsetting the temperature reading from the actual temperature.
- 4. The sensor's temperature (base temperature plus temperature increase from heater) must not exceed  $T_{max} = 125$  °C to have proper electrical functionality of the chip.
- 5. The heater draws a large amount of current once enabled (up to ~50 mA in the highest power setting). Although a dedicated circuitry draws this current smoothly, the power supply must be strong enough to avoid large voltage drops that could provoke a sensor reset.
- 6. If higher heating temperatures are desired, consecutive heating commands must be sent to the sensor. To keep times between consecutive heating pulses minimal, polling of the sensor is advised. The heater shall only be operated in ambient temperatures below 65 °C else it could drive the sensor outside of its maximal operating temperature.

# **5** Physical Specification

## 5.1 Package Description

SHT4xI-Digital is provided in an open-cavity dual flat no lead (DFN) package. The humidity sensor opening is centered on the top side of the package. The sensor chip is made of silicon, hosted on a copper lead frame and overmolded by an epoxy-based mold compound. Exposed bottom side of the leadframe with the metallic contacts is Ni/Pd/Au coated, side walls are bare copper. Moisture sensitivity level (MSL) of 1 according to IPC/JEDEC J-STD-020 is achieved. It is recommended to process the sensors within one year after date of delivery.

## 5.2 Package Outline



Figure 7. Dimensional drawing of SHT4xI-Digital including package tolerances (units mm).







### 5.3 Land Pattern

The land pattern is recommended to be designed according to the used PCB and soldering process together with the physical outer dimensions of the sensor. For reference, the land pattern used with Sensirion's PCBs and soldering processes is given in **Figure 9**.

Soldering of the central die pad is optional. Sensirion recommends to not solder the central die pad because the sensor can reach higher temperatures upon heater activation.



no copper in this area-

**Figure 9**. Recommended land pattern (in mm). Details can vary and depend on used PCBs and solder processes. There shall be no copper under the sensor than at the pin pads. other

#### 5.4 Pin Assignment & Laser Marking

| Pin | Name | 1                                  | O   |   |
|-----|------|------------------------------------|-----|---|
| 1   | SDA  | Serial data, bidirectional         |     | ) |
| 2   | SCL  | Serial clock, unidirectional input |     |   |
| 3   | VDD  | Supply voltage                     | 2   |   |
| 4   | VSS  | Ground                             | ] 2 |   |



**Figure 10.** Pin assignment (transparent top view). Dashed lines are only visible if sensor is viewed from below. The die pad is not directly connected to any pin.

The laser marking consists of two lines, indicated in **Figure 10**. In the first line a filled circle serves as pin-1 indicator and is followed by "SH4". The fourth character will indicate the accuracy class of this product (here "x" serves as place holder). Last "I" indicates the industrial grade. In the second line, the first three characters specify the product characteristics according to positions 7, 8 and 9 of **Table 10**. The second three characters serve as internal batch tracking code.<sup>16</sup>

<sup>&</sup>lt;sup>16</sup> Please note, there will be no change in the laser marking for the protective option (filter membrane and protective foil).



## 5.5 Thermal Information

| Symbol          | Description                               | Heater off, die<br>pad soldered<br>(K/W) | Heater on, die<br>pad soldered<br>(K/W) | Heater off, <b>die pad</b><br><b>not soldered</b><br>(K/W) | Heater on, <b>die pad</b><br><b>not soldered</b><br>(K/W) |
|-----------------|---|--|---|--|---|
| $R_{\theta JA}$ | Junction-to-ambient<br>thermal resistance | 246                                      | 308                                     | 297  | 357   |
| $R_{\theta JC}$ | Junction-to-case<br>thermal resistance    | 189                                      | 255                                     | 191  | 257   |
| $R_{\theta JB}$ | Junction-to-board<br>thermal resistance   | 159                                      | 225                                     | 193  | 258   |
| $\Psi_{JB}$     | Junction-to-board characterization param. | 159                                      | 223                                     | 191  | 254   |
| $\Psi_{JT}$     | Junction-to-top characterization param.   | 38                                       | 105                                     | 44   | 112   |

**Table 9.** Typical values for thermal metrics. In the "heater on" columns a heater power of 200 mW was assumed. Soldering of the die pad is not recommended, therefore the two right hand side columns are bold. Values are based on simulation.

# **6 Protection Options**

### 6.1 Membrane Option

The filter membrane option for SHT4xI family members inherently provides an additional barrier for all pollutants to enter the sensor opening, thus lowering negative influences on the sensing element. Mostly designed to keep particles and dust from accumulating and reducing the response time, the membrane also enables more efficient and easy cleaning, as it helps to reduce liquid intrusion into the sensor opening. Even though not selectively filtering, in general, physical barriers allow to reduce the amount of unwanted chemical contamination and help to remove potentially harmful components by facilitating wiping (flat sensor surface).

The integrated SHT4xI PTFE membrane provides additional protection, from particles, and enables sensor operation in harsh conditions. The membrane has a thickness of 100  $\mu$ m offering a filtration efficiency of >99.99% for particles of 200 nm size and larger. Owing to the high permeability and the small volume between sensing element and membrane, the specified response time of the RH sensor is unaltered.



**Figure 11.** SHT4xI-Digital with integrated PTFE membrane, highlighting the beneficial flat geometry of the SHT4xI-Digital.

To ensure full functionality of the sensor and avoid damaging its integrated filter membrane, when mounting the sensor, follow the reflow soldering process as described in the Handling Instructions [1]. Furthermore the therein described care regarding board wash and cleaning still apply.

### 6.2 Protective Cover

The SHT4xI-Digital will be available with a second protective option, a removable protective cover to protect the sensing element during sensor installation. The sensor will be delivered with the protective cover attached such that the sensor opening is completely covered and sealed. This enables cost-effective brush-over and spray-over application procedures of conformal coating material. Such coating is often required in highly corrosive environments to protect solder joints. In this process the protective cover prevents the sensor opening to be sealed by any coating and to it, the foil can be pulled off with tweezers at the designated non-sticking flap.

The protective cover is made of polyimide making it highly resistant to chemicals and elevated temperatures<sup>17</sup>. To ensure full functionality of the cover, when mounting the sensor, follow the reflow soldering process as described in the Handling Instruction [1].



Figure 12. Sketch of the SHT4xI with attached polyimide foil.<sup>18</sup>

<sup>17</sup>Up to 260 °C

<sup>&</sup>lt;sup>18</sup> This a preliminary sketch only and might be subject to change.



# 7 Quality and Material Contents

Qualification of SHT4xI-Digital is performed based on the JEDEC JESD47 qualification test method. Qualification pending. The device is fully RoHS and WEEE compliant, *e.g.* free of Pb, Cd, and Hg.

For general remarks of best practice in processing humidity sensor please refer to the Handling Instructions for Humidity Sensors [1].

# 8 Tape and Reel Packaging

All specifications for the tape and reel packaging can be found on **Figure 13**. Reel diameters are 13 inch and 8 inch for the 10k and the 2.5k packaging sizes, respectively.



Figure 13. Tape and reel specifications including sensor orientation in pocket (see indication of two sensors on the right side of the tape).



Figure 14. Tape and reel specification including sensor orientation in pocket of sensor with membrane option.

## **9 Product Name Nomenclature**

| Position | Value(s)    | Explanation  |
|----------|-------------|--|
| 1        | S           | Sensirion  |
| 2        | Н           | Humidity Signal  |
| 3        | Т           | Temperature Signal   |
| 4        | 4           | Fourth product generation  |
| 5        | 0 1         | Base accuracy<br>Improved accuracy   |
| 6        | I           | Industrial version   |
| 7        | -           | Delimiter  |
| 8        | A<br>B<br>C | I2C interface with 0x44 address<br>I2C interface with 0x45 address<br>I2C interface with 0x46 address  |
| 9        | D           | DFN package  |
| 10       | 1           | Reserved   |
| 11       | B<br>F<br>P | blank package without membrane<br>package with integrated, patented PTFE membrane<br>package with removable protection cover for conformal coating (coming soon) |
| 12       | -           | Delimiter  |
| 13       | R           | Tape on reel packaging   |
| 14       | 2<br>3      | Packaging article contains 2'500 pieces<br>Packaging article contains 10'000 pieces  |

 Table 10. SHT4xI-Digital product name nomenclature.

# **10 Ordering Information**

| Material Description | Material Number | Details  | Quantity (pcs) |
|----------------------|-----------------|--|----------------|
| SHT40I-AD1B-R2       | 3.000.553       | base RH&T accuracy, 0x44 I2C addr.   | 2'500          |
| SHT40I-AD1F-R2       | 3.000.888       | base RH&T accuracy, 0x44 I2C addr.<br>including patented PTFE membrane         | 2'500          |
| SHT40I-AD1P-R2       | tbd             | base RH&T accuracy, 0x44 I2C addr.<br>including removable protective cover     | 2'500          |
| SHT40I-AD1B-R3       | 3.000.664       | base RH&T accuracy, 0x44 I2C addr.   | 10'000         |
| SHT40I-BD1B-R3       | 3.000.891       | base RH&T accuracy, 0x45 I2C addr.   | 10'000         |
| SHT40I-CD1B-R3       | 3.000.890       | base RH&T accuracy, 0x46 I2C addr.   | 10'000         |
| SHT41I-AD1B-R2       | 3.000.573       | improved RH&T accuracy, 0x44 I2C addr.   | 2'500          |
| SHT41I-AD1F-R2       | 3.000.885       | improved RH&T accuracy, 0x44 I2C addr.<br>including patented PTFE membrane     | 2'500          |
| SHT41I-AD1P-R2       | tbd             | improved RH&T accuracy, 0x44 I2C addr.<br>including removable protective cover | 2'500          |
| SHT41I-AD1B-R3       | 3.000.665       | improved RH&T accuracy, 0x44 I2C addr.   | 10'000         |

 Table 11. SHT4xI-Digital ordering options.

# 11 Bibliography

[1] Sensirion, "Handling Instructions for Humidity Sensors," 2020. [Online]. Available: www.sensirion.com.

# **12 Revision History**

| Date          | Version | Page(s) | Changes   |
|---------------|---------|---------|---|
| November 2021 | 1       | All     | Initial release   |
| November 2022 | 2       | 1       | Updated Device Overview with membrane options                   |
|               |         | 1       | Added Feedback QR Code  |
|               |         | 3       | Added link to snapEDA   |
|               |         | 6       | Added Section 2.4 on water activity measurements                |
|               |         | 7       | Updated Table 4 electrical specs: Supply current "heater on"    |
|               |         | 10      | Corrected erratum in caption of <b>Table 8</b> :                |
|               |         |         | old: " valid for VDD=3.3 V" new: " valid for VDD=5.0 V"         |
|               |         | 10      | Added water activity sensor signal conversion formula           |
|               |         | 12      | Inserted Figure 8 for filter membrane                           |
|               |         | 13      | Footnote 16:no change in laser marking of protective options    |
|               |         | 15      | Added Section 6 on protective options                           |
|               |         | 17      | Inserted Figure 14, tape/reel specifications of membrane option |
|               |         | 18      | Updated product nomenclature                                    |
|               |         | 18      | Updated ordering information in Table 11                        |
|               |         | All     | Reviewed font size, typos, references & general formatting      |

# **Important Notices**

#### Warning, Personal Injury

Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury. Do not use this product for applications other than its intended and authorized use. Before installing, handling, using or servicing this product, please consult the data sheet and application notes. Failure to comply with these instructions could result in death or serious injury.

If the Buyer shall purchase or use SENSIRION products for any unintended or unauthorized application, Buyer shall defend, indemnify and hold harmless SENSIRION and its officers, employees, subsidiaries, affiliates and distributors against all claims, costs, damages and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if SENSIRION shall be allegedly negligent with respect to the design or the manufacture of the product.

#### **ESD** Precautions

The inherent design of this component causes it to be sensitive to electrostatic discharge (ESD). To prevent ESD-induced damage and/or degradation, take customary and statutory ESD precautions when handling this product. See application note "ESD, Latchup and EMC" for more information.

#### Warranty

SENSIRION warrants solely to the original purchaser of this product for a period of 12 months (one year) from the date of delivery that this product shall be of the quality, material and workmanship defined in SENSIRION's published specifications of the product. Within such period, if proven to be defective, SENSIRION shall repair and/or replace this product, in SENSIRION's discretion, free of charge to the Buyer, provided that:

- notice in writing describing the defects shall be given to SENSIRION within fourteen (14) days after their appearance;
- such defects shall be found, to SENSIRION's reasonable satisfaction, to have arisen from SENSIRION's faulty design, material, or workmanship;
- the defective product shall be returned to SENSIRION's factory at the Buyer's expense; and
- the warranty period for any repaired or replaced product shall be limited to the unexpired portion of the original period.

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