# **AEDS-9310** Transmissive Photointerrupter

# **Data Sheet**





### Description

The photointerrupter consists of a Gallium Arsenide infrared light emitting diode and a NPN silicon phototransistor built in a black plastic housing. It is a transmissive subminiature photointerrupter.



Figure 1: Illustrates Basic Configuration of Photointerrupter

## Features

- Non-Contact Sensing
- Infra-Red Wavelength
- Fast Switching Speed
- Mounting Guide Pins
- Dual-in-line Socket Mounting
- RoHS Compliant

#### **Applications**

- Optical Switch
- ATM Machines
- Vending Machines
- Edge, Position Detections
- Office Automation Equipments

#### **Theory of Operation**

The photo-interrupter consists of an Infrared light source and a photo-diode in a single Dual-in-Line package. The photo-interrupter could be mounted onto a PC board with a current-limiting resistor in series externally with the Infrared Emitting Diode. With this, such input voltage for the emitting diode could share the same voltage level as VCC.

Regarding the photo-interrupter output, there will always be current output measured but with the external resistor, RL connected as shown in Figure 1, analog voltage output could then be obtained.

With both the infrared light source and the photo diode in a single package, the photo-interrupter employs transmissive technology to sense obstacles existence, acts as on / off switchers or even to sense lowresolution rotary or linear motions. The photointerrupter is specified for operation over -25 °C to +85 °C temperature range.

As a basic switcher, the photo-interrupter would have a position detecting characteristics as shown in Figure 2. These characteristic diagrams give the relationship between Relative Light Current, IL and Distance of displacement, d. Note that the slot (obstacle) introduced in between the emitting diode and the photo-diode could applied in two directions. One is of X-axis and another would be of Y-axis.

Therefore, with the presence of slot, the photointerrupter would actually give a low logic output. Vice versa, the photo-interrupter will provide a high logic output without the existence of the slot. Refer to Figure 3. Typically, Rise Time, tr and Fall Time tf will have the same value,  $20\mu$ s.

With special design of the slots, periodic presence and absence could be generated. Such output signal is useful in determining low-resolution (>0.5mm pitch) motor rotation positioning and motor spinning speed.



Figure 2: Illustrates Photo-Interrupter Positioning Sensing Characteristics. Obstacles (Slots) could interrupt along X-axis or Y-axis.



Figure 3: Response Time Measurement of Output Signal.



Figure 4: Periodical Output signal could be used to determine the Motor Spinning Speed and Rotation positioning.

Sensing Position Characteristics

# Absolute Maximum Ratings @ TA=25°C

Maximum Rating	Unit			
5	V			
50	mA			
75	mW			
30	V			
5	V			
75	mW			
100	mW			
-25°C to 85°C				
-40°C to 85°C				
260°C for 5 seconds				
	5 50 75 30 5 75 5 75 100 -25°C to 85°C -40°C to 85°C	5 V   50 mA   75 mW   30 V   5 V   75 mW   100 mW   -25°C to 85°C -40°C to 85°C		

# Optical-Electrical Characteristics TA=25°C

Parameter	Symbol	Min.	Тур.	Max.	Unit	Test Conditions
LED Forward voltage	V <sub>F</sub>	-	1.2	1.4	V	I <sub>F</sub> =20mA
LED Reverse Current	I <sub>R</sub>	-	-	10	А	V <sub>R</sub> = 5V
Collector Current	Ι <sub>c</sub>	0.5	-	10	mA	$I_F=20mA$ , $V_{CE}=5V$
Collector dark current	I <sub>CEO</sub>	-	-	100	nA	V <sub>CE</sub> =10V
Collector Emitter saturation voltage	$V_{CE(SAT)}$	-	-	0.4	V	I <sub>e</sub> =0.1mA, E <sub>e</sub> =0.1mW/cm <sup>2</sup>
Rise time	Tr	-	20	100	μs	$V_{CE}$ =5V, R <sub>L</sub> =1k $\Omega$ , I <sub>C</sub> =100mA, d=1mm
Fall time	T <sub>f</sub>	-	20	100	μs	_

### **Outline Drawing**



Tolerance is +/- 0.25 mm (.006") unless otherwise specified Unit: mm (inches)

## **Typical Optical-Electrical Curves**











Figure 9: Spectral Sensitivity (Detecting Side)



Figure 6: Collector Current Vs Forward Voltage



Figure 8: Response Time Vs Load Resistance

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